

Helical Planetary Gearhead Features

Parker planetary gearheads incorporate the latest technology enhancements...

- **Latest technology in seals to reduce heat and wear**
- **Oil lubrication reduces friction and operating temperature, increasing gear life**



Helical Planetary Design

Helical gears have more tooth contact and greater face width than spur gears. This results in higher loads, smoother tooth engagement, quieter operation and lower backlash.

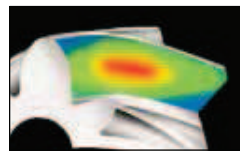


“The Helical Advantage”

Parker planetary gearheads are a superior design with construction integrity to deliver power, speed and accuracy – quietly and efficiently.

HeliCrown®

Parker developed the HeliCrown gear tooth to further optimize Stealth's® performance. Since most vibration occurs at the entry and exit points of a gear tooth, HeliCrown eliminates metal only in these areas, without sacrificing gear strength, producing a quieter and stronger gear.



Power... 30% more torque than comparably sized gearheads

Speed... up to 6,000 RPM input speeds

Accuracy... Less than 3 arc-minutes backlash

Quiet... Less than 68 dB noise

Efficiency... Over 97% efficiency

Plasma Nitriding

Parker's in-house Plasma Nitriding process results in an ideal gear tooth. The surface is very hard (65 Rc) and the core is strong, but flexible (36 Rc). The result is a wear-resistant gear tooth that can withstand heavy shock, ensuring high accuracy for the life of the gearhead.



ServoMount®

Parker's ServoMount design features a balanced input gear supported by a floating bearing. This unique design compensates for motor shaft runout and misalignment, ensuring TRUE alignment of the input sun gear with the planetary section and allowing input speeds up to 6,000 RPM. ServoMount ensures error-free installation to any motor, in a matter of minutes.



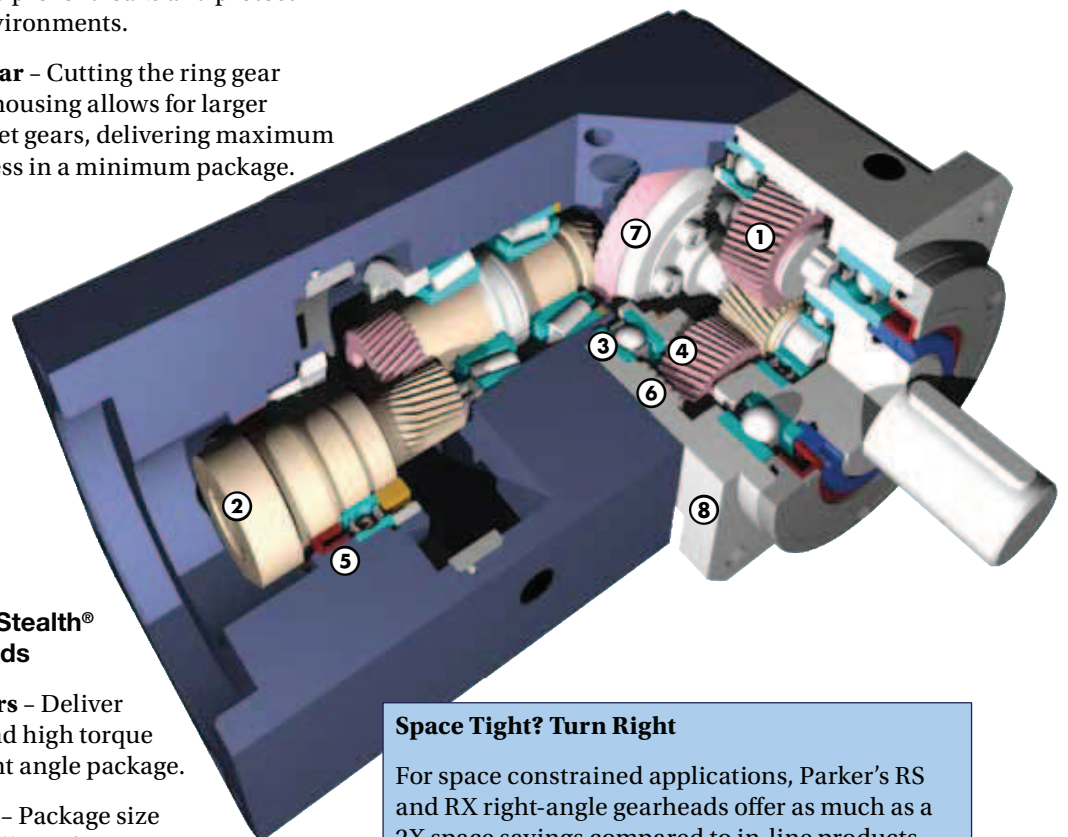
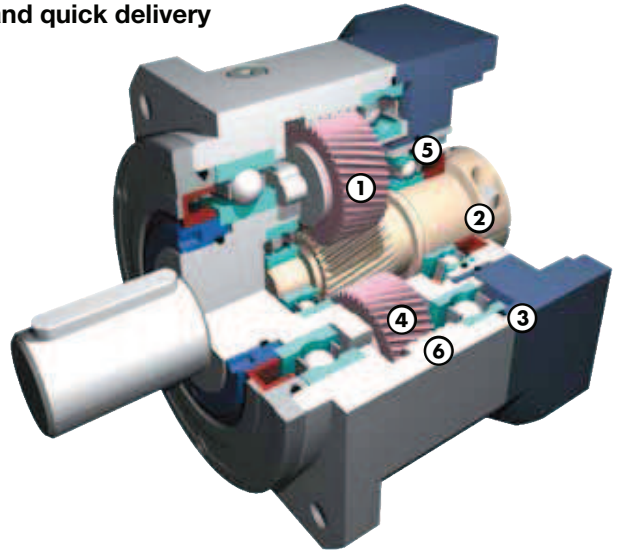
Parker Stealth® planetary gearhead features

Features unique to Generation II Stealth® gearheads

- **Widely spaced angular contact bearings provide higher radial load capacity**
- **Full compliment of needle bearings for increased service life**
- **Universal mounting kits offer easier mounting and quick delivery**

Common features for all Generation I & II Stealth® gearheads

- ① **Helical Planetary** - Provides smooth, quiet operation, high torque and high accuracy.
- ② **ServoMount®** - Motor-mounting design ensures error-free installation and the balanced pinion allows higher input speeds.
- ③ **Precision Bearings** - Provide high speed and high radial and axial load capacity.
- ④ **HeliCrown®** - Parker's proprietary gear tooth geometry ensures quieter operation and higher loads than conventional gears.
- ⑤ **Sealed Unit** - Viton seals and O-Rings provide IP65 protection to prevent leaks and protect against harsh environments.
- ⑥ **Integral Ring Gear** - Cutting the ring gear directly into the housing allows for larger bearing and planet gears, delivering maximum power and stiffness in a minimum package.



Features unique to Stealth® right-angle gearheads

- ⑦ **Spiral Bevel Gears** - Deliver high efficiency and high torque in a compact, right angle package.
- ⑧ **Compact Design** - Package size is the same regardless of ratio.

Space Tight? Turn Right

For space constrained applications, Parker's RS and RX right-angle gearheads offer as much as a 2X space savings compared to in-line products.

Generation II Stealth® Series

RS Generation II Performance Specifications

Parameter	Units	Ratio	RS60 Gen II	RS90 Gen II	RS115 Gen II	RS142 Gen II
Nominal Output Torque ¹⁾ $T_{nom r}$	Nm (in-lb)	5	13 (115)	55 (487)	85 (752)	225 (1992)
		10	24 (212)	80 (708)	160 (1415)	365 (3232)
		15,20,25,50	35 (310)	88 (779)	220 (1947)	430 (3807)
		30,40,100	30 (266)	86 (752)	195 (1726)	310 (2745)
Maximum Acceleration Output Torque ²⁾ $T_{acc r}$	Nm (in-lb)	5	19 (168)	83 (743)	127 (1124)	337 (2984)
		10	36 (320)	120 (743)	240 (2124)	547 (4843)
		15,20,25,50	45 (400)	123 (867)	255 (2257)	645 (5711)
		30,40,100	37 (327)	112 (797)	240 (2124)	465 (4717)
Emergency Stop Output Torque ³⁾ $T_{em r}$	Nm (in-lb)	5	40 (355)	150 (1327)	270 (2390)	625 (5534)
		10	72 (637)	240 (2125)	480 (4248)	1000 (8854)
		15,20,25,50	80 (708)	250 (2213)	510 (4514)	1100 (9739)
		30,40,100	60 (531)	200 (1770)	430 (3806)	830 (7349)
Nominal Input Speed $N_{nom r}$	RPM	5 to 10	3200	2800	2400	2000
		15,20,25,30,40	3700	3300	2900	2500
		50,100	4200	3800	3400	3000
Maximum Input Speed $N_{max r}$ ⁴⁾	RPM	5 – 100	6000	5300	4500	3800
Maximum Radial Load Pr_{max} ^{5,7)}	N (lbs)		1650 (370)	4800 (1080)	7500 (1685)	10,000 (2247)
Maximum Axial Load Pa_{max} ⁶⁾	N (lbs)		2100 (475)	3600 (810)	6800 (1530)	8800 (1976)
Service Life	h		20,000			
Standard Backlash ⁸⁾	arc-min	5 – 10	<14	<12	<12	<10
		15 – 100	<12	<10	<10	<8
Low Backlash ⁸⁾	arc-min	5 – 10	<10	<8	<8	<6
		15 – 100	<8	<6	<6	<4
Efficiency at Nominal Torque	%	5 – 100	94	94	94	94
Noise Level at 3000 RPM ⁹⁾	db	5 – 100	<65	<68	<68	<70
Torsional Stiffness	Nm/arc-min (in-lb/arc-min)	5 – 100	2.5 (22)	10 (90)	22 (195)	42 (372)
Maximum Allowable Case Temperature	° C	5 – 100	-20 to 90			
Lubrication		5 – 100	Per Maintenance Schedule			
Mounting Position		5 – 100	Any			
Degree of Protection			IP65			
Maximum Weight	kg (lbs)	5 – 100	2.0 (4.4)	6.0 (13.2)	11.0 (24.2)	24 (52)

1) At nominal speed $N_{nom r}$.

2) Parker MotionSizer sizing software available for free download at parkeremotion.com.

3) Maximum of 1000 stops.

4) For intermittent operation.

5) Max radial load applied to the center of the shaft at 100 rpm.

6) Max axial load at 100 rpm.

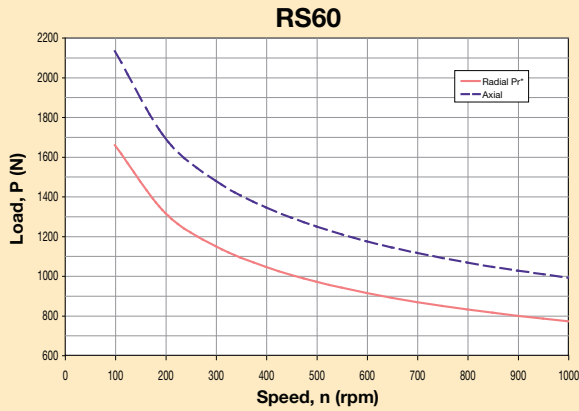
7) For combined radial and axial load consult factory.

8) Measured at 2% of rated torque.

9) Measure at 1m.

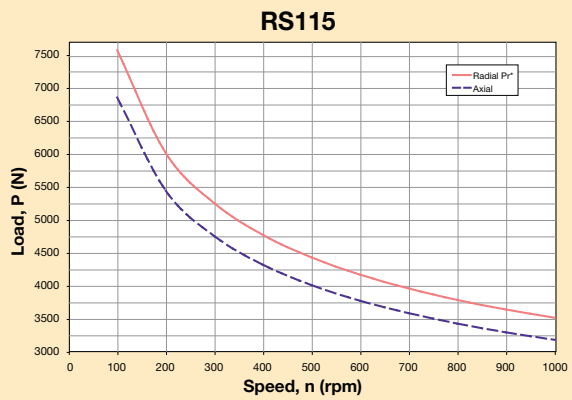
RS Generation II Output Shaft Load Rating

Formulas below graphs are used to calculate radial load (Prx) at any distance "X" from the gearhead mounting surface:



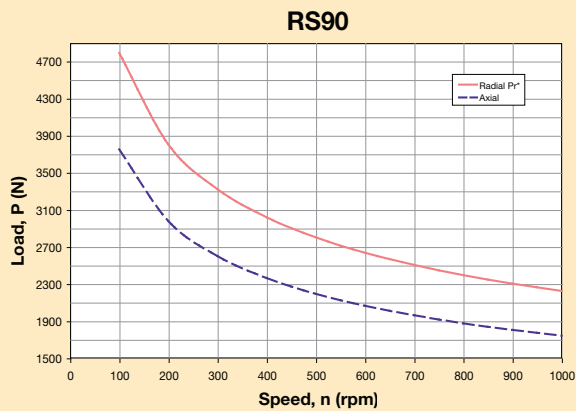
$$Pr_x = Pr * 75 \text{ mm} / (49 + X)$$

$$Pr_x = Pr * 2.95 \text{ in} / (1.93 \text{ in} + X)$$



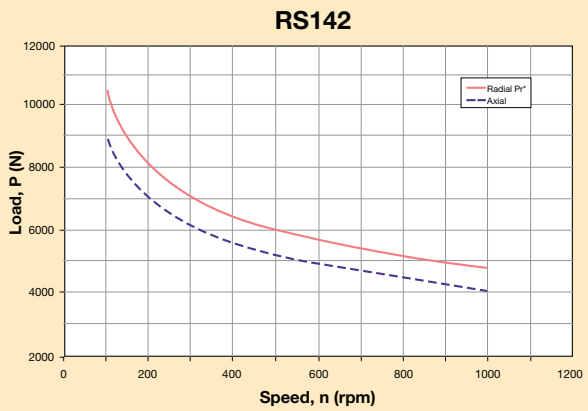
$$Pr_x = Pr * 124 \text{ mm} / (81 + X)$$

$$Pr_x = Pr * 4.88 \text{ in} / (3.19 \text{ in} + X)$$



$$Pr_x = Pr * 96 \text{ mm} / (62 + X)$$

$$Pr_x = Pr * 3.78 \text{ in} / (2.44 \text{ in} + X)$$



$$Pr_x = Pr * 156 \text{ mm} / (93 + X)$$

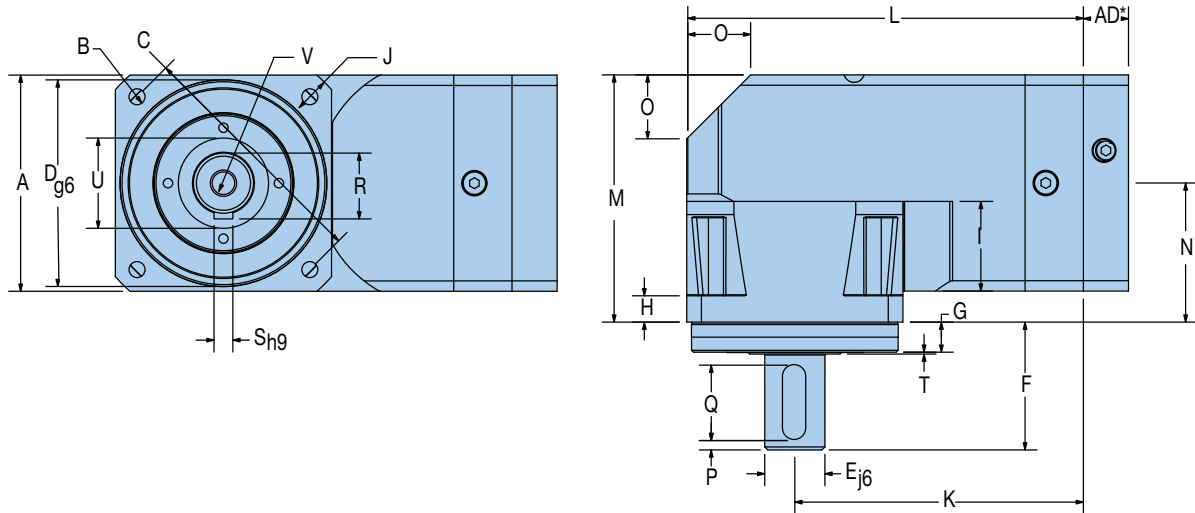
$$Pr_x = Pr * 6.14 \text{ in} / (3.66 \text{ in} + X)$$

* Radial load applied to center of the shaft.

Generation II Stealth® Series

RS Generation II Dimensions

Free 3D Solid Models and drawings available at parkermotion.com



Metric Frame Sizes

Frame Size	A		B		C		D		E		F		G		H	
	Square Flange		Bolt Hole		Bolt Circle		Pilot Diameter		Output Shaft Diameter		Output Shaft Length		Pilot Thickness		Flange Thickness	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RS60	62	2.441	5.5	0.217	70	2.756	50	1.969	16	0.630	40	1.575	11	0.433	8	0.315
RS90	90	3.543	6.5	0.256	100	3.937	80	3.150	22	0.866	52	2.047	15	0.591	10	0.394
RS115	115	4.528	8.5	0.335	130	5.118	110	4.331	32	1.260	68	2.677	16	0.630	14	0.551
RS142	142	5.591	11.0	0.433	165	6.496	130	5.118	40	1.575	102	4.016	20	0.787	15	0.591

Frame Size	I		J		K		L		M		N		O		P	
	Recess Length		Housing Recess		Distance to Output Centerline		Housing Length		Housing Width		Distance to Input Centerline		Taper Distance		Distance from Shaft End	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
RS60	23.5	0.925	5.0	0.197	66.0	2.598	124.7	4.909	78.0	3.071	47.0	1.850	15	0.591	2	0.079
RS90	33.0	1.299	6.5	0.256	132.0	5.197	177.0	6.969	103.0	4.055	58.0	2.283	27	1.063	3	0.118
RS115	42.0	1.653	7.5	0.295	153.5	6.043	211.0	8.307	132.0	5.177	74.0	2.913	34	1.339	5	0.197
RS142	56.5	2.224	10.0	0.394	198.5	7.815	269.5	10.610	158.2	6.228	87.2	3.433	42	1.654	5	0.197

Frame Size	Q		R		S		T		U		V
	Keyway Length		Key Height		Keyway Width		Shoulder Height		Shoulder Diameter		Tap & Depth (end of shaft)
	mm	in	mm	in	mm	in	mm	in	mm	in	
RS60	25	0.984	18.0	0.709	5	0.197	0.5	0.020	22	0.866	M5x8
RS90	32	1.260	24.5	0.965	6	0.236	0.5	0.020	35	1.378	M8x16
RS115	40	1.575	35.0	1.378	10	0.394	1	0.039	45	1.772	M12x25
RS142	63	2.480	43.0	1.693	12	0.472	2.5	0.098	78	3.071	M16x32

RS Generation II Universal Mounting Kits*

Adapter Length “AD” Dimension

Frame Size	Motor Shaft Length		Gearhead Adapter Length	
	mm	in	mm	in
60	16 – 35	0.630 – 1.378	16.5	0.65
	35.1 – 41	1.382 – 1.614	22.5	0.886
90	20 – 40	0.787 – 1.575	20	0.787
	40.1 – 48	1.579 – 1.890	28.5	1.122
115	22 – 50	0.866 – 1.969	24	0.945
	50.1 – 61	1.972 – 2.402	35	1.378
142	26 – 62	1.023 – 2.441	30	1.181
	62.1 – 82	2.445 – 3.228	50	1.969

* Know your motor and need our mounting kit part number? See page 29 or use our Motor Mounting Search Tool on our website at: www.parkermotion.com

RS Generation II Inertia

All moment of inertia values are as reflected at the input of the gearhead

Ratio	Units*	RS60	RS90	RS115	RS142
5	kg-cm ²	0.2200	0.8100	2.5000	9.4000
	in-lb-sec ²	0.000195	0.000717	0.002213	0.008319
10	kg-cm ²	0.1900	0.6100	1.9000	6.7000
	in-lb-sec ²	0.000168	0.000540	0.001682	0.005929
15	kg-cm ²	0.1800	0.6000	1.7000	6.6000
	in-lb-sec ²	0.150000	0.000531	0.001505	0.005841
20	kg-cm ²	0.1700	0.5100	1.4000	5.2000
	in-lb-sec ²	0.000150	0.000451	0.001239	0.004602
25	kg-cm ²	0.1600	0.4200	1.3000	4.5000
	in-lb-sec ²	0.000142	0.000372	0.001151	0.003983
30	kg-cm ²	0.1800	0.6000	1.7000	6.7000
	in-lb-sec ²	0.000159	0.000531	0.001505	0.005929
40	kg-cm ²	0.1700	0.5100	1.4000	5.2000
	in-lb-sec ²	0.000150	0.000451	0.001239	0.004602
50	kg-cm ²	0.1500	0.4000	1.1000	3.4000
	in-lb-sec ²	0.000133	0.000354	0.000974	0.003009
100	kg-cm ²	0.1500	0.4000	1.1000	3.4000
	in-lb-sec ²	0.000133	0.000354	0.000974	0.003009

* Note: 1 kg-cm² = 0.000885 in-lb-sec²